

Minimization Problem with Smooth Components

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- MiniMax problem
- Gradient Mapping for MiniMax problem ;
- The complexity of gradient and optimal method;
- Optimization with functional constraint (General constrained optimization problem)
- Constrained Minimization Problem

MiniMax Problem

- Objective function is composed with several components.
- The simplest problem of that type is *minimax* problem.
- We'll focus on *smooth* minimax problem:

$$\min_{x \in Q} \left[f(x) = \max_{1 \leq i \leq m} f_i(x) \right]$$

where $f_i \in \mathcal{S}_{\mu,L}^{1,1}(R^n)$, $i = 1, \dots, m$ and Q is a closed convex set.

- $f(x)$: the *max-type function* composed by the *components* $f_i(x)$.

• In general, $f(x)$ is not differentiable.

• We use $f \in \mathcal{S}_{\mu,L}^{1,1}(R^n)$ to denote all the $f_i \in \mathcal{S}_{\mu,L}^{1,1}(R^n)$.

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General Minimization Problem

$$\min f_0(x) \quad (1)$$

$$s.t. f_i(x) \leq 0, \quad i = 1, \dots, m \quad (2)$$

$$x \in Q \quad (3)$$

parametric max-type function

$$f(t; x) = \max\{f_0(x) - t; f_i(x)\}$$

Will be showed later:

- the optimal value of $f_0(x)$ corresponds to the root t of $f(t; x) = 0$;
- minimax problem is used as a subroutine to solve (1);

Linearization

max-type function $f(x) = \max_{1 \leq i \leq m} f_i(x)$

linearization of $f(x)$ $f(\bar{x}; x) = \max_{1 \leq i \leq m} [f_i(\bar{x}) + \langle f'_i(\bar{x}), x - \bar{x} \rangle]$

Essentially, linearization over each component.

Properties

- $f(\bar{x}; x) + \frac{\mu}{2} \|x - \bar{x}\|^2 \leq f(x) \leq f(\bar{x}; x) + \frac{L}{2} \|x - \bar{x}\|^2$;
- $x^* \in Q \Leftrightarrow f(x^*; x) \geq f(x^*; x^*) = f(x^*)$.
- $f(x) \geq f(x^*) + \frac{\mu}{2} \|x - x^*\|^2$
- the solution x^* exists and unique.

Lemma 2.3.1

$$f(\bar{x}; x) + \frac{\mu}{2} \|x - \bar{x}\|^2 \leq f(x) \leq f(\bar{x}; x) + \frac{L}{2} \|x - \bar{x}\|^2$$

- $f_i \in \mathcal{S}_{\mu, L}^{1,1}(R^n)$
- For **strongly convex** function, we have

$$\begin{aligned} f_i(x) &\geq f_i(\bar{x}) + \langle f'_i(\bar{x}, x - \bar{x}) \rangle + \frac{\mu}{2} \|x - \bar{x}\|^2 \\ &= f(\bar{x}; x) + \frac{\mu}{2} \|x - \bar{x}\|^2 \end{aligned}$$

Take the max on both sides: $f(x) \geq f(\bar{x}; x) + \frac{\mu}{2} \|x - \bar{x}\|^2$

- For **Lipshitz continuous** function, it follows

$$\begin{aligned} f_i(x) &\leq f_i(\bar{x}) + \langle f'_i(\bar{x}, x - \bar{x}) \rangle + \frac{L}{2} \|x - \bar{x}\|^2 \\ &= f(\bar{x}; x) + \frac{L}{2} \|x - \bar{x}\|^2 \end{aligned}$$

- **max operation keeps the property as smooth strongly convex function.**

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Theorem 2.3.1: $x^* \in Q \Leftrightarrow f(x^*; x) \geq f(x^*; x^*) = f(x^*)$

\Leftarrow As $f(x) \geq f(\bar{x}; x) + \frac{\mu}{2} \|x - \bar{x}\|^2$, we have

$$f(x) \geq f(x^*; x) + \frac{\mu}{2} \|x - x^*\|^2 \geq f(x^*; x^*) + 0 = f(x^*)$$

\Rightarrow Prove by contradiction: if $f(x^*; x) < f(x^*)$, then for $1 \leq i \leq m$

$$f_i(x^*) + \langle f'_i(\bar{x}; x^*), x - x^* \rangle < f(x^*) = \max_{1 \leq i \leq m} f_i(x^*)$$

Define $\phi_i(\alpha) = f_i(x^* + \alpha(x - x^*))$, $\alpha \in [0, 1]$

So either $\phi_i(0) \equiv f_i(x^*) < f(x^*)$ or

$$\phi_i(0) = f(x^*), \quad \phi'_i(0) = \langle f'_i(x^*), x - x^* \rangle < 0$$

So small enough α ,

$$f_i(x^* + \alpha(x - x^*)) = \phi_i(\alpha) < f(x^*) \quad \forall 1 \leq i \leq m$$

contradiction!

Linearization achieves its minimum at x^*

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Corollary 2.3.1

$$f(x) \geq f(x^*) + \frac{\mu}{2} \|x - x^*\|^2$$

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So if x^* exists, it must be unique.

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Theorem 3.2

Let a max-type function $f(x) \in \mathcal{S}_\mu^1(\mathbb{R}^n)$, $\mu > 0$, and Q be a closed convex set. Then the solution x^* exists and unique.

- Let $\bar{x} \in Q$, consider the set $\bar{Q} = \{x \in Q | f(x) \leq f(\bar{x})\}$.
- Transform to a problem as

$$\min\{f(x) | x \in \bar{Q}\}$$

- Need to show \bar{Q} is bounded.

$$\begin{aligned} f(\bar{x}) &\geq f_i(x) \geq f_i(\bar{x}) + \langle f'(\bar{x}), x - \bar{x} \rangle + \frac{\mu}{2} \|x - \bar{x}\|^2 \\ \implies \frac{\mu}{2} \|x - \bar{x}\|^2 &\leq \|f'(\bar{x})\| \cdot \|x - \bar{x}\| + f(\bar{x}) - f_i(\bar{x}) \end{aligned}$$

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Quick Summary

MiniMax, though generally not smooth, share all the properties as minimizing smooth strongly convex functions over simple convex set.

Linearization

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As expected, share most of the properties as minimization over simple convex set.

Gradient Mapping

Similar as the case on minimization with convex set, we can define gradient mapping as follows:

$$f_\gamma(\bar{x}; x) = f(\bar{x}; x) + \frac{\gamma}{2} \|x - \bar{x}\|^2 \quad (\text{quadratic approximation}) \quad (4)$$

$$f^*(\bar{x}; \gamma) = \min_{x \in Q} f_\gamma(\bar{x}; x) \quad (5)$$

$$x_f(\bar{x}; \gamma) = \operatorname{argmin}_{x \in Q} f_\gamma(\bar{x}; x) \quad (6)$$

$$g_f(\bar{x}; \gamma) = \gamma(\bar{x} - x_f(\bar{x}; \gamma)) \quad (\text{gradient mapping}) \quad (7)$$

The only difference is the linearization part $f(\bar{x}; x)$.

- When $m = 1$ (only one component), the same as minimization over simple convex set;
- the linearization point \bar{x} does not necessarily belong to Q ;
- $f_\gamma(\bar{x}; x)$ is a max-type function composed with components:

$$f_i(\bar{x}) + \langle f'_i(\bar{x}), x - \bar{x} \rangle + \frac{\gamma}{2} \|x - \bar{x}\|^2 \in \mathcal{S}_{\gamma, \gamma}^{1,1}(R^n), \quad i = 1, \dots, m \quad (8)$$

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Linearization and gradient mapping

$f(x)$ is bounded by the linearization (plus quadratic term), Could we somehow bound the linearization part with gradient mapping?

Theorem 2.3.3

Let $f \in \mathcal{S}_{\mu,L}^{1,1}(R^n)$, then for all $x \in Q$

$$f(\bar{x}; x) \geq f^*(\bar{x}; \gamma) + \langle g_f(\bar{x}; \gamma), x - \bar{x} \rangle + \frac{1}{2\gamma} \|g_f(\bar{x}; \gamma)\|^2 \quad (9)$$

$$f(\bar{x}; x) = f_\gamma(\bar{x}; x) - \frac{\gamma}{2} \|x - \bar{x}\|^2 \quad (10)$$

$$\geq \underbrace{f_\gamma(\bar{x}; x_f) + \frac{\gamma}{2} (\|x - x_f\|^2 - \|x - \bar{x}\|^2)}_{f_\gamma(\bar{x}; x) \in \mathcal{S}_{\gamma,\gamma}^{1,1}(R^n)} \quad (11)$$

$$= f^*(\bar{x}; \gamma) + \frac{\gamma}{2} \langle (\bar{x} - x_f, 2x - x_f - \bar{x}) \rangle \quad (12)$$

$$= f^*(\bar{x}; \gamma) + \frac{\gamma}{2} \langle (\bar{x} - x_f, 2(x - \bar{x}) + (\bar{x} - x_f)) \rangle \quad (13)$$

$$= f^*(\bar{x}; \gamma) + \langle g_f, x - \bar{x} \rangle + \frac{1}{2\gamma} \|g_f\|^2 \quad (14)$$

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Properties with respect to gradient mapping

Since $f(\bar{x}; x) \geq f^*(\bar{x}; \gamma) + \langle g_f(\bar{x}; \gamma), x - \bar{x} \rangle + \frac{1}{2\gamma} \|g_f(\bar{x}; \gamma)\|^2$

Corollary 2.3.2 Let $f \in S_{\mu, L}^{1,1}(R^n)$ and $\gamma \geq L$. Then:

1. For any $x \in Q$ and $\bar{x} \in R^n$ we have:

$$f(x) \geq f(x_f(\bar{x}; \gamma)) + \langle g_f(\bar{x}; \gamma), x - \bar{x} \rangle + \frac{1}{2\gamma} \|g_f(\bar{x}; \gamma)\|^2 + \frac{\mu}{2} \|x - \bar{x}\|^2. \quad (2.3.7)$$

2. If $\bar{x} \in Q$ then

$$f(x_f(\bar{x}; \gamma)) \leq f(\bar{x}) - \frac{1}{2\gamma} \|g_f(\bar{x}; \gamma)\|^2, \quad (2.3.8)$$

3. For any $\bar{x} \in R^n$ we have:

$$\langle g_f(\bar{x}; \gamma), \bar{x} - x^* \rangle \geq \frac{1}{2\gamma} \|g_f(\bar{x}; \gamma)\|^2 + \frac{\mu}{2} \|x^* - \bar{x}\|^2. \quad (2.3.9)$$

Proof:

Assumption $\gamma \geq L$ implies that $f^*(\bar{x}; \gamma) \geq f(x_f(\bar{x}; \gamma))$. Therefore (2.3.7) follows from (2.3.6) since

$$f(x) \geq f(\bar{x}; x) + \frac{\mu}{2} \|x - \bar{x}\|^2$$

for all $x \in R^n$ (see Lemma 2.3.1).

Using (2.3.7) with $x = \bar{x}$, we get (2.3.8), and using (2.3.7) with $x = x^*$, we get (2.3.9) since $f(x_f(\bar{x}; \gamma)) - f(x^*) \geq 0$. \square

Lemma 2.3.2 For any $\gamma_1, \gamma_2 > 0$ and $\bar{x} \in R^n$ we have:

$$f^*(\bar{x}; \gamma_2) \geq f^*(\bar{x}; \gamma_1) + \frac{\gamma_2 - \gamma_1}{2\gamma_1\gamma_2} \|g_f(\bar{x}; \gamma_1)\|^2.$$

Proof:

Denote $x_i = x_f(\bar{x}; \gamma_i)$, $g_i = g_f(\bar{x}; \gamma_i)$, $i = 1, 2$. In view of (2.3.6), we have:

$$f(\bar{x}; x) + \frac{\gamma_2}{2} \|x - \bar{x}\|^2 \geq f^*(\bar{x}; \gamma_1) + \langle g_1, x - \bar{x} \rangle + \frac{1}{2\gamma_1} \|g_1\|^2 + \frac{\gamma_2}{2} \|x - \bar{x}\|^2 \quad (2.3.10)$$

for all $x \in Q$. In particular, for $x = x_2$ we obtain:

$$\begin{aligned} f^*(\bar{x}; \gamma_2) &= f(\bar{x}; x_2) + \frac{\gamma_2}{2} \|x_2 - \bar{x}\|^2 \\ &\geq f^*(\bar{x}; \gamma_1) + \langle g_1, x_2 - \bar{x} \rangle + \frac{1}{2\gamma_1} \|g_1\|^2 + \frac{\gamma_2}{2} \|x_2 - \bar{x}\|^2 \\ &= f^*(\bar{x}; \gamma_1) + \frac{1}{2\gamma_1} \|g_1\|^2 - \frac{1}{\gamma_2} \langle g_1, g_2 \rangle + \frac{1}{2\gamma_2} \|g_2\|^2 \\ &\geq f^*(\bar{x}; \gamma_1) + \frac{1}{2\gamma_1} \|g_1\|^2 - \frac{1}{2\gamma_2} \|g_1\|^2. \end{aligned}$$

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Gradient Method: Comparison

General Scheme for Gradient Method:

$$\begin{aligned}x_0 &\in Q, \\x_{k+1} &= x_k - hg_f(x_k; L), \quad k = 0, \dots\end{aligned}$$

On minimization over Minimax Problem (Same as over simple set)

If we choose $h \leq \frac{1}{L}$ in General Scheme for Gradient Method, then

$$\|x_k - x^*\|^2 \leq (1 - \mu h)^k \|x_0 - x^*\|^2. \quad (15)$$

If $h = \frac{1}{L}$

$$\|x_k - x^*\|^2 \leq \left(1 - \frac{\mu}{L}\right)^k \|x_0 - x^*\|^2 \quad (16)$$

the gradient method has the same rate of convergence as in the smooth case.

Let $r_k = \|x_k - x^*\|$, $g = g_f(x_k; L)$, (As $2\langle g, x_k - x^* \rangle \geq \frac{1}{\gamma} \|g\|^2 + \mu \|x_k - x^*\|^2$)

$$\begin{aligned}r_{k+1}^2 &= \|x_k - x^* - hg_f\|^2 \\&= r_k^2 - 2h\langle g_f, x_k - x^* \rangle + h^2 \|g_f\|^2 \\&\leq (1 - h\mu)r_k^2 + h\left(h - \frac{1}{L}\right) \|g_f\|^2 \leq \left(1 - \frac{\mu}{L}\right)r_k^2.\end{aligned}$$

Minimization Method - Optimal Method

- **Step 1: define the estimate sequence** Assume that we have $x_0 \in Q$. Define

$$\phi_0(x) = \phi_0^* + \frac{\gamma_0}{2} \|x - v_0\|^2, \quad (17)$$

$$\phi_k(x) = (1 - \alpha_k)\phi_k + \alpha_k \left[f(x_Q) + \langle g_Q, x - y_k \rangle + \frac{1}{2\gamma} \|g_Q\|^2 + \frac{\mu}{2} \|x - y_k\|^2 \right], \quad (18)$$

where $x_Q = x_Q(y_k; L)$ and $g_Q = g_Q(y_k; L)$.

- **Step 2: rewrite the sequence** $\{\phi_k(x)\}$ For $k \geq 0$, we have

$$\phi_k(x) = \phi_k^* + \frac{\gamma_k}{2} \|x - v_k\|^2, \quad (19)$$

where the following recursive rules are defined for γ_k , v_k , and ϕ_k^* as

$$\gamma_{k+1} = (1 - \alpha_k)\gamma_k + \alpha_k\mu, \quad (20)$$

$$v_{k+1} = \frac{1}{\gamma_{k+1}} [(1 - \alpha_k)\gamma_k v_k + \alpha_k\mu y_k - \alpha_k g_Q], \quad (21)$$

$$\begin{aligned} \phi_{k+1}^* &= (1 - \alpha_k)\phi_k^* + \alpha_k f(x_Q) + \left(\frac{\alpha_k}{2L} - \frac{\alpha_k^2}{2\gamma_{k+1}} \right) \|g_Q\|^2 \\ &\quad + \frac{\alpha_k(1 - \alpha_k)\gamma_k}{\gamma_{k+1}} \left(\frac{\mu}{2} \|y_k - v_k\|^2 + \langle g_Q, v_k - y_k \rangle \right). \end{aligned} \quad (22)$$

- **Step 3: ensure $\phi_k^* \geq f(x_k)$** Using the inequality

$$f(x_k) \geq f(x_Q) + \langle g_Q, x_k - y_k \rangle + \frac{1}{2\gamma} \|g_Q\|^2 + \frac{\mu}{2} \|x_k - y_k\|^2, \quad (23)$$

we come to the following lower bound

$$\begin{aligned} \phi_{k+1}^* &\geq (1 - \alpha_k)f(x_k) + \alpha_k f(x_Q) + \left(\frac{\alpha_k}{2L} - \frac{\alpha_k^2}{2\gamma_{k+1}} \right) \|g_Q\|^2 \\ &\quad + \frac{\alpha_k(1 - \alpha_k)\gamma_k}{\gamma_{k+1}} \left(\frac{\mu}{2} \|y_k - v_k\|^2 + \langle g_Q, v_k - y_k \rangle \right) \\ &\geq f(x_Q) + \left(\frac{1}{2L} - \frac{\alpha_k^2}{2\gamma_{k+1}} \right) \|g_Q\|^2 + (1 - \alpha_k) \left\langle g_Q, \frac{\alpha_k\gamma_k}{\gamma_{k+1}} (v_k - y_k) + x_k - y_k \right\rangle. \end{aligned}$$

Therefore, we choose

$$\begin{aligned} x_{k+1} &= x_Q, \\ L\alpha_k^2 &= (1 - \alpha_k)\gamma_k + \alpha_k\mu = \gamma_{k+1}, \\ y_k &= \frac{1}{\gamma_k + \alpha_k\mu} (\alpha_k\gamma_k v_k + \gamma_{k+1}x_k). \end{aligned}$$

Constant Step Scheme 3 for Simple Set

1 Choose $x_0 \in Q$ and $\alpha_0 \in (0, 1)$. Set $y_0 = x_0$, $q = \mu/L$.

2 k th iteration ($k \geq 0$).

- Compute $f(y_k)$ and $f'(y_k)$. Set

$$x_{k+1} = x_Q. \quad (24)$$

- Compute $\alpha_{k+1} \in (0, 1)$ from the equation

$$\alpha_{k+1}^2 = (1 - \alpha_{k+1})\alpha_k^2 + q\alpha_{k+1},$$

and set

$$\beta_k = \frac{\alpha_k(1 - \alpha)}{\alpha_k^2 + \alpha_{k+1}}, \quad y_{k+1} = x_{k+1} + \beta_k(x_{k+1} - x_k). \quad (25)$$

Note that only $\{x_k\}$ are feasible for Q , while $\{y_k\}$ can not be guaranteed to be feasible.

Completely identical to unconstrained case. The convergent rate is exactly the same as unconstrained case.

Theorem 2.3.5 *Let the max-type function f belong to $S_{\mu,L}^{1,1}(R^n)$. If in (2.3.12) we take $\alpha_0 \geq \sqrt{\frac{\mu}{L}}$, then*

$$f(x_k) - f^* \leq \left[f(x_0) - f^* + \frac{\gamma_0}{2} \|x_0 - x^*\|^2 \right] \times \min \left\{ \left(1 - \sqrt{\frac{\mu}{L}} \right)^k, \frac{4L}{(2\sqrt{L} + k\sqrt{\gamma_0})^2} \right\},$$

where $\gamma_0 = \frac{\alpha_0(\alpha_0 L - \mu)}{1 - \alpha_0}$.

$$\text{Scheme for } f \in \mathcal{S}_{\mu,L}^{1,1}(\mathbb{R}^n) \quad (2.3.13)$$

0. Choose $x_0 \in Q$. Set $y_0 = x_0$, $\beta = \frac{\sqrt{L}-\sqrt{\mu}}{\sqrt{L}+\sqrt{\mu}}$.

1. k th iteration ($k \geq 0$). Compute $\{f_i(y_k)\}$ and $\{f'_i(y_k)\}$. Set

$$x_{k+1} = x_f(y_k; L), \quad y_{k+1} = x_{k+1} + \beta(x_{k+1} - x_k).$$

Theorem 2.3.6 *For this scheme we have:*

$$f(x_k) - f^* \leq 2 \left(1 - \sqrt{\frac{\mu}{L}}\right)^k (f(x_0) - f^*). \quad (2.3.14)$$

Proof:

Scheme (2.3.13) corresponds to $\alpha_0 = \sqrt{\frac{\mu}{L}}$. Then $\gamma_0 = \mu$ and we get (2.3.14) since $f(x_0) \geq f^* + \frac{\mu}{2} \|x_0 - x^*\|^2$ in view of Corollary 2.3.1. \square

Problem 2.3.16

$$\min f_0(x) \quad (26)$$

$$\text{s.t. } f_i(x) \leq 0, \quad i = 1, \dots, m \quad (27)$$

$$x \in Q \quad (28)$$

parametric max-type function

$$f(t; x) = \max\{f_0(x) - t; f_i(x)\}$$

$f(t; \cdot)$ are strongly convex in x . For any t , $x^*(t)$ exists and unique.

$$f^*(t) = \min_{x \in Q} f(t; x)$$

We'll try to get close to the solution using a process **based on the approximate values of the function $f^*(t)$** (aka. *sequential quadratic programming*)

Lemma 2.3.4

Lemma 2.3.4 *Let t^* be the optimal value of the problem (2.3.16). Then*

$$f^*(t) \leq 0 \quad \text{for all } t \geq t^*,$$

$$f^*(t) > 0 \quad \text{for all } t < t^*.$$

Proof:

Let x^* be the solution to (2.3.16). If $t \geq t^*$ then

$$f^*(t) \leq f(t; x^*) = \max\{f_0(x^*) - t; f_i(x^*)\} \leq \max\{t^* - t; f_i(x^*)\} \leq 0.$$

Suppose that $t < t^*$ and $f^*(t) \leq 0$. Then there exists $y \in Q$ such that

$$f_0(y) \leq t < t^*, \quad f_i(y) \leq 0, \quad i = 1, \dots, m.$$

Thus, t^* cannot be the optimal value of (2.3.16). □

Note that, as t increases, $f^*(t)$ decreases in a sense.

Hence, **the smallest root of the function $f^*(t)$ corresponds to the optimal value of the problem of functional constraint.**

Our goal is to form a process of finding the root.

Properties of $f^*(t)$

Lemma 2.3.5 For any $\Delta \geq 0$ we have:

$$f^*(t) - \Delta \leq f^*(t + \Delta) \leq f^*(t).$$

Proof:

Indeed,

$$\begin{aligned} f^*(t + \Delta) &= \min_{x \in Q} \max_{1 \leq i \leq m} \{f_0(x) - t - \Delta; f_i(x)\} \\ &\leq \min_{x \in Q} \max_{1 \leq i \leq m} \{f_0(x) - t; f_i(x)\} = f^*(t), \\ f^*(t + \Delta) &= \min_{x \in Q} \max_{1 \leq i \leq m} \{f_0(x) - t; f_i(x) + \Delta\} - \Delta \\ &\geq \min_{x \in Q} \max_{1 \leq i \leq m} \{f_0(x) - t; f_i(x)\} - \Delta = f^*(t) - \Delta. \quad \square \end{aligned}$$

- Thus, $f^*(t)$ decreases in t and is Lipschitz continuous with the constant equal to 1.
- Keep in mind that here the property is satisfied for any max-type function like $f_\mu(\bar{x}; x)$ and $f_L(\bar{x}; x)$.

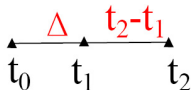
Lemma 2.3.6

For any $t_1 < t_2$ and $\Delta \geq 0$, we have

$$f^*(t_1 - \Delta) \geq f^*(t_1) + \Delta \frac{f^*(t_1) - f^*(t_2)}{t_2 - t_1} = f^*(t_1) - \Delta \frac{f^*(t_2) - f^*(t_1)}{t_2 - t_1} \quad (29)$$

Let $t_0 = t_1 - \Delta$, $\alpha = \frac{\Delta}{t_2 - t_0}$, then $t_1 = (1 - \alpha)t_0 + \alpha t_2$, so

$$(29) : \equiv f^*(t_1) \leq (1 - \alpha)f^*(t_0) + \alpha f^*(t_2)$$



Let $x_\alpha = (1 - \alpha)x^*(t_0) + \alpha x^*(t_2)$. We have:

$$\begin{aligned} f^*(t_1) &\leq \max_{1 \leq i \leq m} \{f_0(x_\alpha) - t_1; f_i(x_\alpha)\} \\ &\leq \max_{1 \leq i \leq m} \{(1 - \alpha)(f_0(x^*(t_0)) - t_0) + \alpha(f_0(x^*(t_2)) - t_2); (1 - \alpha)f_i(x^*(t_0)) + \alpha f_i(x^*(t_2))\} \\ &\leq (1 - \alpha) \max_{1 \leq i \leq m} \{f_0(x^*(t_0)) - t_0; f_i(x^*(t_0))\} + \alpha \max_{1 \leq i \leq m} \{f_0(x^*(t_2)) - t_2; f_i(x^*(t_2))\} \\ &= (1 - \alpha)f^*(t_0) + \alpha f^*(t_2), \end{aligned}$$

Lemma 2.3.5

For any $\Delta > 0$, we have:

$$f^*(t) - \Delta \leq f^*(t + \Delta) \leq f^*(t)$$

Lemma 2.3.6

For any $t_1 < t_2$ and $\Delta \geq 0$, we have

$$f^*(t_1 - \Delta) \geq f^*(t_1) + \Delta \frac{f^*(t_1) - f^*(t_2)}{t_2 - t_1} = f^*(t_1) - \Delta \frac{f^*(t_2) - f^*(t_1)}{t_2 - t_1}$$

- Both Lemmas are valid for **any** parametric max-type functions.

Linearization of $f(t; x)$:

$$f(t; \bar{x}; x) = \max_{1 \leq i \leq m} \{f_0(x) + \langle f'_0(\bar{x}), x - \bar{x} \rangle - t; f_i(x) + \langle f'_i(\bar{x}), x - \bar{x} \rangle\}$$

$$f_\gamma(t; \bar{x}; x) = f(t; \bar{x}; x) + \frac{\gamma}{2} \|x - \bar{x}\|^2 \quad (30)$$

$$f^*(t; \bar{x}; \gamma) = \min_{x \in Q} f_\gamma(t; \bar{x}; x) \quad (31)$$

$$x_f(t; \bar{x}; \gamma) = \operatorname{argmin}_{x \in Q} f_\gamma(t; \bar{x}; x) \quad (32)$$

$$g_f(t; \bar{x}; \gamma) = \gamma(\bar{x} - x_f(t; \bar{x}; \gamma)) \quad (33)$$

g_f is the *constrained gradient mapping*; \bar{x} is not necessarily in Q .

$$f_\gamma(t; \bar{x}; x) = f(t; \bar{x}; x) + \frac{\gamma}{2} \|x - \bar{x}\|^2$$

- $f_\gamma(t; \bar{x}; x)$ is itself a max-type function;
- $f_\gamma(t; \bar{x}; x) \in \mathcal{S}_{\gamma, \gamma}^{1,1}(R^n)$. So for any t , the constrained gradient mapping is well defined;
- $f_\mu(t; \bar{x}; x) \leq f(t; x) \leq f_L(t; \bar{x}; x)$, as $f(t; x) \in \mathcal{S}_{\mu, L}^{1,1}(R^n)$; Hence

$$f_\mu^*(t; \bar{x}; x) \leq f^*(t) \leq f_L^*(t; \bar{x}; x)$$

- For any $\bar{x} \in R^n$, $\gamma > 0$, $\Delta \geq 0$ and $t_1 < t_2$, we have

$$f^*(t_1 - \Delta; \bar{x}; \gamma) \geq f^*(t_1; \bar{x}; \gamma) + \frac{\Delta}{t_2 - t_1} (f^*(t_1; \bar{x}; \gamma) - f^*(t_2; \bar{x}; \gamma))$$

- $f^*(t; \bar{x}; \mu) \geq f^*(t; \bar{x}; L) - \frac{L-\mu}{2\mu L} \|g_f(t; \bar{x}; L)\|^2$

$$f_\gamma(t; \bar{x}; x) = f(t; \bar{x}; x) + \frac{\gamma}{2} \|x - \bar{x}\|^2$$

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- $f^*(t; \bar{x}; \mu) \geq f^*(t; \bar{x}; L) - \frac{L-\mu}{2\mu L} \|g_f(t; \bar{x}; L)\|^2$

$$f_\gamma(t; \bar{x}; x) = f(t; \bar{x}; x) + \frac{\gamma}{2} \|x - \bar{x}\|^2$$

- $f_\gamma(t; \bar{x}; x)$ is itself a max-type function;
- $f_\gamma(t; \bar{x}; x) \in \mathcal{S}_{\gamma, \gamma}^{1,1}(R^n)$. So for any t , the constrained gradient mapping is well defined;
- $f_\mu(t; \bar{x}; x) \leq f(t; x) \leq f_L(t; \bar{x}; x)$, as $f(t; x) \in \mathcal{S}_{\mu, L}^{1,1}(R^n)$; Hence

$$f_\mu^*(t; \bar{x}; x) \leq f^*(t) \leq f_L^*(t; \bar{x}; x)$$

- For any $\bar{x} \in R^n$, $\gamma > 0$, $\Delta \geq 0$ and $t_1 < t_2$, we have

$$f^*(t_1 - \Delta; \bar{x}; \gamma) \geq f^*(t_1; \bar{x}; \gamma) + \frac{\Delta}{t_2 - t_1} (f^*(t_1; \bar{x}; \gamma) - f^*(t_2; \bar{x}; \gamma))$$

- $f^*(t; \bar{x}; \mu) \geq f^*(t; \bar{x}; L) - \frac{L-\mu}{2\mu L} \|g_f(t; \bar{x}; L)\|^2$

- We are interested in finding the root of the function $f^*(t)$. We focus on the approximation of $f_\gamma(t; \bar{x}; \gamma)$.

$$t^*(\bar{x}; t) = \text{root}_t(f^*(t; \bar{x}; \mu))$$

- The root of the lower-bound quadratic approximation.
- Notice that the notation is a little confusing here $t^*(\bar{x}; t)$ actually depends on \bar{x} , not t .

Lemma 2.3.7 *Let $\bar{x} \in R^n$ and $\bar{t} < t^*$ are such that*

$$f^*(\bar{t}; \bar{x}; \mu) \geq (1 - \kappa)f^*(\bar{t}; \bar{x}; L)$$

for some $\kappa \in (0, 1)$. Then $\bar{t} < t^(\bar{x}, \bar{t}) \leq t^*$. Moreover, for any $t < \bar{t}$ and $x \in R^n$ we have:*

$$f^*(t; x; L) \geq 2(1 - \kappa)f^*(\bar{t}; \bar{x}; L) \sqrt{\frac{\bar{t} - t}{t^*(\bar{x}, \bar{t}) - \bar{t}}}$$

- We are interested in finding the root of the function $f^*(t)$. We focus on the approximation of $f_\gamma(t; \bar{x}; \gamma)$.

$$t^*(\bar{x}; t) = \text{root}_t(f^*(t; \bar{x}; \mu))$$

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for some $\kappa \in (0, 1)$. Then $\bar{t} < t^(\bar{x}, \bar{t}) \leq t^*$. Moreover, for any $t < \bar{t}$ and $x \in R^n$ we have:*

$$f^*(t; x; L) \geq 2(1 - \kappa)f^*(\bar{t}; \bar{x}; L) \sqrt{\frac{\bar{t} - t}{t^*(\bar{x}, \bar{t}) - \bar{t}}}$$

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for some $\kappa \in (0, 1)$. Then $\bar{t} < t^(\bar{x}, \bar{t}) \leq t^*$. Moreover, for any $t < \bar{t}$ and $x \in R^n$ we have:*

$$f^*(t; x; L) \geq 2(1 - \kappa)f^*(\bar{t}; \bar{x}; L)\sqrt{\frac{\bar{t} - t}{t^*(\bar{x}, \bar{t}) - \bar{t}}}.$$

Proof:

Since $\bar{t} < t^*$, we have:

$$0 < f^*(\bar{t}) \leq f^*(\bar{t}; \bar{x}; L) \leq \frac{1}{1 - \kappa}f^*(\bar{t}; \bar{x}; \mu).$$

Thus, $f^*(\bar{t}; \bar{x}; \mu) > 0$ and therefore $t^*(\bar{x}, \bar{t}) > \bar{t}$ since $f^*(t; \bar{x}; \mu)$ decreases in t .

Denote $\Delta = \bar{t} - t$, Then,

$$f^*(t; x; L) \geq f^*(t) \geq f^*(t; \bar{x}; \mu) \quad (34)$$

$$\geq f^*(\bar{t}; \bar{x}; \mu) + \frac{\Delta}{t^*(\bar{x}, t) - \bar{t}} \left[f^*(\bar{t}; \bar{x}; \mu) - \underbrace{f^*(t^*(\bar{x}, t), \bar{x}, \mu)}_{=0} \right]$$

$$\geq (1 - \kappa) \left(1 + \frac{\Delta}{t^*(\bar{x}; t) - \bar{t}} \right) f^*(\bar{t}; \bar{x}; L) \quad (35)$$

$$\geq (1 - \kappa) 2 \sqrt{\frac{\Delta}{t^*(\bar{x}; t) - \bar{t}}} f^*(\bar{t}; \bar{x}; L) \quad (36)$$

$$= 2(1 - \kappa) f^*(\bar{t}; \bar{x}; L) \sqrt{\frac{\bar{t} - t}{t^*(\bar{x}; t) - \bar{t}}} \quad (37)$$

Constrained Minimization Scheme

(2.3.22)

0. Choose $x_0 \in Q$ and $t_0 < t^*$. Choose $\kappa \in (0, \frac{1}{2})$ and the accuracy $\epsilon > 0$.

1. k th iteration ($k \geq 0$).

a). Generate the sequence $\{x_{k,j}\}$ by the minimax method (2.3.13) as applied to the max-type function $f(t_k; x)$ with the starting point $x_{k,0} = x_k$. If

$$f^*(t_k; x_{k,j}; \mu) \geq (1 - \kappa)f^*(t_k; x_{k,j}; L)$$

then stop the internal process and set $j(k) = j$,

$$j^*(k) = \arg \min_{0 \leq j \leq j(k)} f^*(t_k; x_{k,j}; L),$$

$$x_{k+1} = x_f(t_k; x_{k,j^*(k)}; L).$$

Global Stop: Terminate the whole process if at some iteration of the internal scheme we have $f^*(t_k; x_{k,j}; L) \leq \epsilon$.

b). Set $t_{k+1} = t^*(x_{k,j(k)}, t_k)$.

□

Essentially two steps:

- Given t , find x until the lower bound $f(t; \bar{x}; \mu)$ and the upper bound $f(t; \bar{x}; L)$ of $f(t, \bar{x})$ is not too distant; Then pick the minimum one during the internal process;
- Given x , update t via finding the root of the lower bound;
QCQP:

of the function

$$f^*(t; \bar{x}; \mu) = \min_{x \in Q} f_\mu(t; \bar{x}; x),$$

where $f_\mu(t; \bar{x}; x)$ is a max-type function composed with the components

$$f_0(\bar{x}) + \langle f'_0(\bar{x}), x - \bar{x} \rangle + \frac{\mu}{2} \|x - \bar{x}\|^2 - t,$$

$$f_i(\bar{x}) + \langle f'_i(\bar{x}), x - \bar{x} \rangle + \frac{\mu}{2} \|x - \bar{x}\|^2, \quad i = 1, \dots, m.$$

In view of Lemma 2.3.4, it is the optimal value of the following minimization problem:

$$\min [f_0(\bar{x}) + \langle f'_0(\bar{x}), x - \bar{x} \rangle + \frac{\mu}{2} \|x - \bar{x}\|^2],$$

$$\text{s.t. } f_i(\bar{x}) + \langle f'_i(\bar{x}), x - \bar{x} \rangle + \frac{\mu}{2} \|x - \bar{x}\|^2 \leq 0, \quad i = 1, \dots, m,$$

$$x \in Q.$$

- The master process is continued until the upper bound function is close enough to 0 ($< \epsilon$)
- We start from a $t_0 < t^*$, and increases t gradually.

- Here, we only focus on analytical complexity of this method.
- The total cost is of the order

$$\ln \frac{t_0 - t^*}{\epsilon} \sqrt{\frac{L}{\mu}} \ln \sqrt{\frac{L}{\mu}}$$

- This value differs from the lower bound for the unconstrained minimization problem by a factor of $\ln \frac{L}{\mu}$. (Not quite sure)
- Thus, the scheme is **suboptimal** for constrained optimization problems. But we cannot say more since the specific lower complexity bounds for constrained minimization are not known.
- We'll estimate the complexity of the master process;
- Then estimate the complexity for the internal process (given t , estimate an x);
- Finally, we get the total complexity.

- Here, we only focus on analytical complexity of this method.
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- This value differs from the lower bound for the unconstrained minimization problem by a factor of $\ln \frac{L}{\mu}$. (Not quite sure)
- Thus, the scheme is **suboptimal** for constrained optimization problems. But we cannot say more since the specific lower complexity bounds for constrained minimization are not known.
- We'll estimate the complexity of the master process;
- Then estimate the complexity for the internal process (given t , estimate an x);
- Finally, we get the total complexity.

Lemma 2.3.8: complexity of master process

Lemma 2.3.8

$$f^*(t_k; x_{k+1}; L) \leq \frac{t^* - t_0}{1 - \kappa} \left[\frac{1}{2(1 - \kappa)} \right]^k$$

$$\text{Let } \beta = \frac{1}{2(1 - \kappa)} (< 1 \text{ as } \kappa < 0.5) \quad \delta_k = \frac{f^*(t_k; x_{k,j(k)}; L)}{\sqrt{t_{k+1} - t_k}}$$

Lemma 2.3.7

For $t < \bar{t} < t^*(\bar{x}, \bar{t}) \leq t^*$, we have

$$f^*(t; \bar{x}; L) \geq 2(1 - \kappa) f^*(\bar{t}; \bar{x}; L) \sqrt{\frac{\bar{t} - t}{t^*(\bar{x}; t) - \bar{t}}} \quad (38)$$

Let $t = t_{k-1}$, $\bar{t} = t_k$, $t^*(\bar{x}; t) = t_{k+1}$ (As $t_{k+1} = t^*(x_{k,j(k)}, t_k)$), we have

$$2(1 - \kappa) \frac{f^*(t_k; x_{k,j(k)}; L)}{\sqrt{t_{k+1} - t_k}} \leq \frac{f^*(t_{k-1}; x_{k-1,j(k-1)}; L)}{\sqrt{t_k - t_{k-1}}} \implies \delta_k \leq \beta \delta_{k-1} \quad (39)$$

$$f^*(t_k; x_{k,j(k)}; L) = \delta_k \sqrt{t_{k+1} - t_k} \leq \beta^k \delta_0 \sqrt{t_{k+1} - t_k} \quad (40)$$

$$= \beta^k f^*(t_0; x_{0,j(0)}; L) \sqrt{\frac{t_{k+1} - t_k}{t_1 - t_0}} \quad (41)$$

Lemma 2.3.8: complexity of master process

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$$f^*(t_k; x_{k+1}; L) \leq \frac{t^* - t_0}{1 - \kappa} \left[\frac{1}{2(1 - \kappa)} \right]^k$$

$$\text{Let } \beta = \frac{1}{2(1 - \kappa)} (< 1 \text{ as } \kappa < 0.5) \quad \delta_k = \frac{f^*(t_k; x_{k,j(k)}; L)}{\sqrt{t_{k+1} - t_k}}$$

Lemma 2.3.5

For any $\Delta > 0$, we have:

$$f^*(t) - \Delta \leq f^*(t + \Delta) \leq f^*(t)$$

Let $t_1 = t_0 + \Delta$, we have $t_1 - t_0 \geq f^*(t_0; x_{0,j(0)}; \mu)$. So

$$f^*(t_k; x_{k,j(k)}; L) = \beta^k f^*(t_0; x_{0,j(0)}; L) \sqrt{\frac{t_{k+1} - t_k}{t_1 - t_0}} \quad (42)$$

$$\leq \beta^k f^*(t_0; x_{0,j(0)}; L) \sqrt{\frac{t_{k+1} - t_k}{f^*(t_0; x_{0,j(0)}; \mu)}} \quad (43)$$

$$\leq \frac{\beta^k}{1 - \kappa} \sqrt{f^*(t_0; x_{0,j(0)}; \mu)(t_{k+1} - t_k)} \leq \frac{\beta^k}{1 - \kappa} \sqrt{f^*(t_0)(t_0 - t^*)} \quad (44)$$

$$\leq \frac{t^* - t_0}{1 - \kappa} \left[\frac{1}{2(1 - \kappa)} \right]^k \quad (\text{As } f^*(t_0) \leq t^* - t_0) \quad (45)$$

Lemma 2.3.8: complexity of master process

Master Process

$$f^*(t_k; x_{k+1}; L) \leq \frac{t^* - t_0}{1 - \kappa} \left[\frac{1}{2(1 - \kappa)} \right]^k < \epsilon \implies N(\epsilon) = \frac{1}{\ln[2(1 - \kappa)]} \ln \frac{t^* - t_0}{(1 - \kappa)\epsilon}$$

Lemma 2.3.10 For all k , $0 \leq k \leq N$, we have:

$$j(k) \leq 1 + \sqrt{\frac{L}{\mu}} \cdot \ln \frac{2(L-\mu)\Delta_k}{\kappa\mu\Delta_{k+1}}.$$

Corollary 2.3.3

$$\sum_{k=0}^N j(k) \leq (N+1) \left[1 + \sqrt{\frac{L}{\mu}} \cdot \ln \frac{2(L-\mu)}{\kappa\mu} \right] + \sqrt{\frac{L}{\mu}} \cdot \ln \frac{\Delta_0}{\Delta_{N+1}}.$$

Lemma 2.3.11

$$j^* \leq 1 + \sqrt{\frac{L}{\mu}} \cdot \ln \frac{2(L-\mu)\Delta_{N+1}}{\kappa\mu\epsilon}.$$

Corollary 2.3.4

$$j^* + \sum_{k=0}^N j(k) \leq (N+2) \left[1 + \sqrt{\frac{L}{\mu}} \cdot \ln \frac{2(L-\mu)}{\kappa\mu} \right] + \sqrt{\frac{L}{\mu}} \cdot \ln \frac{\Delta_0}{\epsilon}.$$

As $N(\epsilon) = \frac{1}{\ln[2(1-\kappa)]} \ln \frac{t^* - t_0}{(1-\kappa)\epsilon}$, the total cost is:

$$\begin{aligned} & \left[\frac{1}{\ln[2(1-\kappa)]} \ln \frac{t_0 - t^*}{(1-\kappa)\epsilon} + 2 \right] \cdot \left[1 + \sqrt{\frac{L}{\mu}} \cdot \ln \frac{2(L-\mu)}{\kappa\mu} \right] \\ & + \sqrt{\frac{L}{\mu}} \cdot \ln \left(\frac{1}{\epsilon} \cdot \max_{1 \leq i \leq m} \{f_0(x_0) - t_0; f_i(x_0)\} \right). \end{aligned} \tag{2.3.26}$$