

Learning Nonparametric Kernel Matrices from Pairwise Constraints

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Nonparametric Kernel Learning

- Existing methods all assume certain parametric form of the kernel;
- Or a linear combination of provided kernels.
- This work focus on non-parametric kernel learning from both labeled and unlabeled data.
- Actually, here kernel learning is more appropriate considered as a similarity matrix which must be semipositive definite.

Problem Formulation

• Given: unlabeled data and some side information (i.e. mustlink (S), cannot-link (D))

$$T_{i,j} = \begin{cases} +1 & (\mathbf{x}_i, \mathbf{x}_j) \in \mathcal{S} \\ -1 & (\mathbf{x}_i, \mathbf{x}_j) \in \mathcal{D} \\ 0 & \text{otherwise} \end{cases}$$

• Goal: Identify a kernel matrix that is consistent with all the pairwise constraints.

$$\underset{Z = V^{\top}V}{\arg\min} \ \|V\|_{2}^{2} + c \sum_{(i,j) \in (\mathcal{S} \cup \mathcal{D})} \max(0, 1 - T_{i,j} Z_{i,j})$$

Use Graph Laplacian as Regularizer

- The previous formulation dose not take into consideration the input pattern of data instances.
- Use Laplacian regularizer:

$$l(V, S) = \sum_{i,j=1}^{n} \frac{S_{i,j}}{\sqrt{d_i d_j}} \|\mathbf{v}_i - \mathbf{v}_j\|_2^2 = \operatorname{tr}(VLV^{\top})$$

- Here, different from spectral clustering, v_i and v_j are vectors.
- So the objective is:

$$\underset{Z=V^{\top}V}{\operatorname{arg\,min}} \ \operatorname{tr}(VLV^{\top}) + c \sum_{(i,j) \in (\mathcal{S} \cup \mathcal{D})} \max{(0,1-T_{i,j}Z_{i,j})}$$



Primal Formulation

$$\underset{Z=V^{\top}V}{\arg\min} \ \operatorname{tr}(VLV^{\top}) + c \sum_{(i,j) \in (\mathcal{S} \cup \mathcal{D})} \max(0, 1 - T_{i,j}Z_{i,j})$$

As
$$\operatorname{tr}(VLV^{\top}) = \operatorname{tr}(LV^{\top}V) = \operatorname{tr}(LZ)$$
.





$$\underset{Z,\epsilon}{\operatorname{arg\,min}} \quad \sum_{i,j=1}^{N} L_{i,j} Z_{i,j} + c \sum_{(i,j) \in (\mathcal{S} \cup \mathcal{D})} \epsilon_{i,j}$$
(3)
s. t.
$$\forall (i,j) \in (\mathcal{S} \cup \mathcal{D}), \ T_{i,j} Z_{i,j} \ge 1 - \epsilon_{i,j}, \epsilon_{i,j} \ge 0$$
$$Z \succeq 0$$

#var = N*N+|S|+|D|

Dual Formulation

$$\mathcal{L} = \sum_{i,j=1}^{N} L_{i,j} Z_{i,j} + c \sum_{(i,j) \in (\mathcal{S} \cup \mathcal{D})} \epsilon_{i,j}$$

$$- \sum_{(i,j) \in (\mathcal{S} \cup \mathcal{D})} Q_{i,j} (T_{i,j} Z_{i,j} - 1 + \epsilon_{i,j})$$

$$- \sum_{(i,j) \in (\mathcal{S} \cup \mathcal{D})} \xi_{i,j} \epsilon_{i,j} - \operatorname{tr}(MZ)$$

$$\frac{\partial \mathcal{L}}{\partial \epsilon_{i,j}} = c - Q_{i,j} - \xi_{i,j} = 0 \to Q_{i,j} \le c$$

$$\frac{\partial \mathcal{L}}{\partial Z_{i,j}} = L_{i,j} - Q_{i,j} T_{i,j} - M_{i,j} = 0 \to L \succeq Q \otimes T$$

$$\underset{Q}{\operatorname{arg\,max}} \quad \sum_{(i,j)\in\mathcal{S}} Q_{i,j} + \sum_{(i,j)\in\mathcal{D}} Q_{i,j}$$
s. t.
$$0 \leq Q_{i,j} \leq c, \ \forall (i,j) \in (\mathcal{S} \cup \mathcal{D})$$

$$L \succeq Q \otimes T$$



#var is equivalent to number of pairwise constraints

Efficient Dual Algorithm

- Using SDP solver to solve dual formulation first.
- Recover the primal kernel matrix Z efficiently based on KKT conditions:

$$M = L - Q \otimes T, \qquad MZ = 0$$

- Z can be factorized as $Z = UBU^{\top}$ where U is the eigenvector of M corresponding eig-value 0.
- $|B| \le |S| + |D| + 1$
- $Arr Rank(L)=n-1, Rank(Q \otimes T) \leq |S|+|D|,$
- * Rank(M)>=n-1-|S|-|D|. Hence, the number of eigenvectors for zero eigenvalue $\leq |S|+|D|+1$

Reformulated Primal

• Plug in the factorization of Z, we have

$$\underset{B\succeq 0}{\operatorname{arg\,min}} \quad \sum_{i,j=1}^{N} L_{i,j} Z_{i,j} + c \sum_{(i,j)\in(\mathcal{S}\cup\mathcal{D})} \epsilon_{i,j}$$
s. t.
$$\forall (i,j)\in(\mathcal{S}\cup\mathcal{D}), \ T_{i,j} Z_{i,j} \geq 1 - \epsilon_{i,j}, \epsilon_{i,j} \geq 0$$

$$Z = UBU^{\top}$$

$$\underset{(i,j)\in(\mathcal{S}\cup\mathcal{D})}{\operatorname{arg\,min}} \operatorname{tr}(BU^{\top}LU) + c \sum_{(i,j)\in(\mathcal{S}\cup\mathcal{D})} \epsilon_{i,j}$$
 (6)

s. t.
$$\forall (i,j) \in (\mathcal{S} \cup \mathcal{D}), \ T_{i,j} \mathbf{u}_i^{\top} B \mathbf{u}_j \ge 1 - \epsilon_{i,j}$$

 $\forall (i,j) \in (\mathcal{S} \cup \mathcal{D}), \epsilon_{i,j} \ge 0$
 $B \succ 0$ SDP with

SDP with smaller #var

Algorithm Overview

- Solve Dual problem first obtain the dual matrix.
- Get the Langrange multiplier M

$$M = L - Q \otimes T, \qquad MZ = 0$$

- Calculate its eigen vector of zero eigen value.
- Solve the simplified primal problem:

arg min
$$\operatorname{tr}(BU^{\top}LU) + c \sum_{(i,j)\in(\mathcal{S}\cup\mathcal{D})} \epsilon_{i,j} \qquad (6)$$
s. t.
$$\forall (i,j)\in(\mathcal{S}\cup\mathcal{D}), \ T_{i,j}\mathbf{u}_{i}^{\top}B\mathbf{u}_{j} \geq 1 - \epsilon_{i,j}$$

$$\forall (i,j)\in(\mathcal{S}\cup\mathcal{D}), \epsilon_{i,j}\geq 0$$

$$B\succeq 0$$

• Recover kernel matrix $Z = UBU^{\top}$

SMO-like algorithm for Dual

- Principle of SMO: Each iteration
 - · with respect to small number of vars.
 - · Closed-form solution.
- Here, for the dual, we optimize in terms of just one entry in the matrix.

$$\underset{Q}{\operatorname{arg\,max}} \sum_{(i,j)\in\mathcal{S}} Q_{i,j} + \sum_{(i,j)\in\mathcal{D}} Q_{i,j}$$
s. t.
$$0 \leq Q_{i,j} \leq c, \ \forall (i,j) \in (\mathcal{S} \cup \mathcal{D})$$

$$L \succeq Q \otimes T$$



$$\underset{Q_{k,l}}{\operatorname{arg\,max}} \quad Q_{k,l} \tag{7}$$
 s. t.
$$0 \le Q_{i,j} \le c, \ A^{k,l} - T_{k,l} Q_{k,l} I^{k,l} \succeq 0$$

S

SMO-like Dual

$$\underset{Q_{k,l}}{\operatorname{arg\,max}} \quad Q_{k,l} \tag{7}$$

s. t.
$$0 \le Q_{i,j} \le c, A^{k,l} - T_{k,l}Q_{k,l}I^{k,l} \succeq 0$$

where matrix $A^{k,l}$ is defined as

$$A^{k,l} = L - (\tilde{Q} - \tilde{Q}_{k,l}I^{k,l}) \otimes T. \tag{8}$$

Note $I^{k,l}$ is a $n \times n$ matrix and is defined as

$$[I^{k,l}]_{i,j} = \begin{cases} 1 & (k=i \text{ and } l=j) \\ 1 & (k=j \text{ and } l=i) \\ 0 & \text{otherwise} \end{cases}$$

Closed-form Solution (1)

• Rewrite the constraint as follows:

$$\begin{pmatrix} A_1 & W \\ W^{\top} & A_2 \end{pmatrix}$$

where $W \in \mathbb{R}^{(n-2)\times 2}$, $A_2 \in \mathbb{R}^{(n-2)\times (n-2)}$, and A_1 is

$$A_{1} = \begin{pmatrix} L_{k,k} & L_{k,l} - Q_{k,l} T_{k,l} \\ L_{k,l} - Q_{k,l} T_{k,l} & L_{l,l} \end{pmatrix}$$

- So $A_1 \succeq W^{\top} A_2^{-1} W$
- Let $W^{\top} A_2^{-1} W \equiv G = \begin{pmatrix} G_{1,1} & G_{1,2} \\ G_{2,1} & G_{2,2} \end{pmatrix}$

$$\begin{pmatrix} L_{k,k} - G_{1,1} & L_{k,l} - Q_{k,l} T_{k,l} - G_{1,2} \\ L_{k,l} - Q_{k,l} T_{k,l} - G_{1,2} & L_{l,l} - G_{2,2} \end{pmatrix} \succeq 0$$

Closed-form Solution (2)

1.
$$L_{k,k} - G_{1,1} \ge 0$$
,

2.
$$L_{l,l} - G_{2,2} \ge 0$$
, and

3. the determinant of the above matrix is non-negative, i.e., $(G_{1,2} + T_{k,l}Q_{k,l} - L_{k,l})^2 \le (L_{k,k} - G_{1,1})(L_{l,l} - G_{2,2}).$

$$\max_{Q_{k,l}} Q_{k,l}$$
s.t. $0 \le Q_{k,l} \le c$

$$|G_{1,2} + T_{k,l}Q_{k,l} - L_{k,l}| \le \mu_{k,l}$$

$$Q_{k,l} = \min(c, \mu_{k,l} - T_{k,l}G_{1,2} + T_{k,l}L_{k,l})$$

Avoid the matrix inverse

• W=(W_a; W_b)
$$W^{\top}A_2^{-1}W \equiv G = \begin{pmatrix} G_{1,1} & G_{1,2} \\ G_{2,1} & G_{2,2} \end{pmatrix}$$



$$G_{a,b} = \mathbf{w}_a^{\mathsf{T}} A_2^{-1} \mathbf{w}_b$$

$$\max_{\mathbf{x}} \quad -\mathbf{x}^{\top} A_2 \mathbf{x} + 2\mathbf{w}_a^{\top} \mathbf{x}$$

$$\rightarrow \mathbf{w}_a^{\top} A_2^{-1} \mathbf{w}_a$$

(Can be solved efficiently using conjugate gradient methods without matrix inverse)

$$\mathbf{w}_a^{\top} A_2^{-1} \mathbf{w}_b = \frac{1}{2} \left((\mathbf{w}_a + \mathbf{w}_b)^{\top} A_2^{-1} (\mathbf{w}_a + \mathbf{w}_b) - \mathbf{w}_a^{\top} A_2^{-1} \mathbf{w}_a - \mathbf{w}_b^{\top} A_2^{-1} \mathbf{w}_b \right)$$

SMO-like Overview

- Optimize with respect to only one var.
- Get closed-form solution.

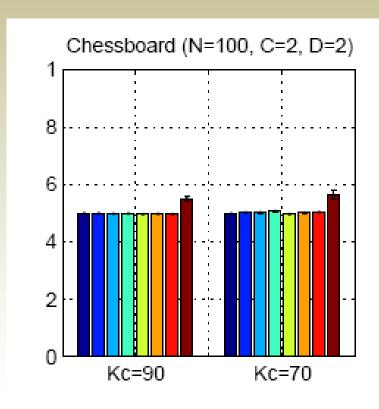
$$Q_{k,l} = \min(c, \mu_{k,l} - T_{k,l}G_{1,2} + T_{k,l}L_{k,l})$$

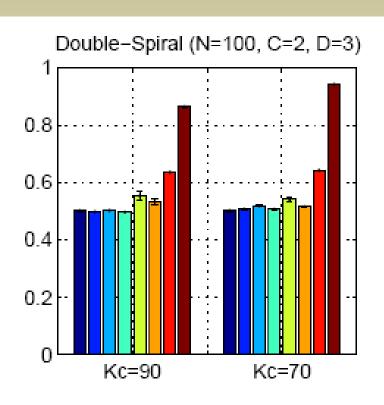
• In this computation, avoid the computation of matrix inverse:

$$\begin{aligned} \mathbf{w}_a^\top A_2^{-1} \mathbf{w}_b &= \\ \frac{1}{2} \Big((\mathbf{w}_a + \mathbf{w}_b)^\top A_2^{-1} (\mathbf{w}_a + \mathbf{w}_b) - \mathbf{w}_a^\top A_2^{-1} \mathbf{w}_a - \mathbf{w}_b^\top A_2^{-1} \mathbf{w}_b \Big) \end{aligned}$$

Experiments

- K-means
- Constrained K-means + RCA, Xing, RBF, MPK, LRK, NPK







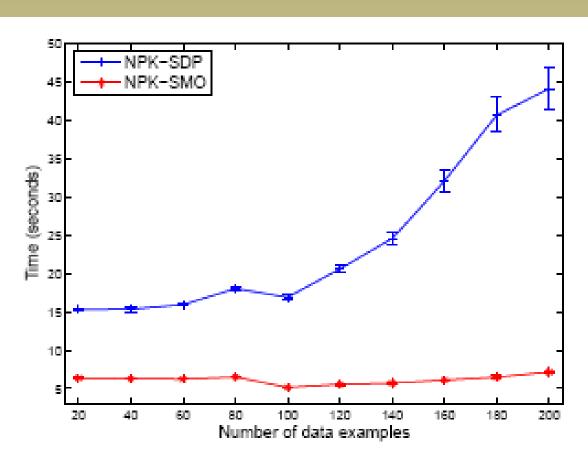


Figure 3. Time cost of different numbers of data examples. The number of pairwise constraints is fixed to 100.



Conclusions

- Use Laplacian as regularization
- Efficient SDP solver.
- But this method is transductive.
- Still too costly.
- Is it sensitive to the Laplacian?
- How to construct an optimal Laplacian?